

Intra-beam IP Feedback Studies for the 380 GeV CLIC Beam Delivery System

R.M. Bodenstern, P.N. Burrows, John Adams Institute – University of Oxford, Oxford, UK
 J. Snuverink, John Adams Institute – Royal Holloway University of London, Egham, UK
 F. Plassard – CERN, Geneva, Switzerland



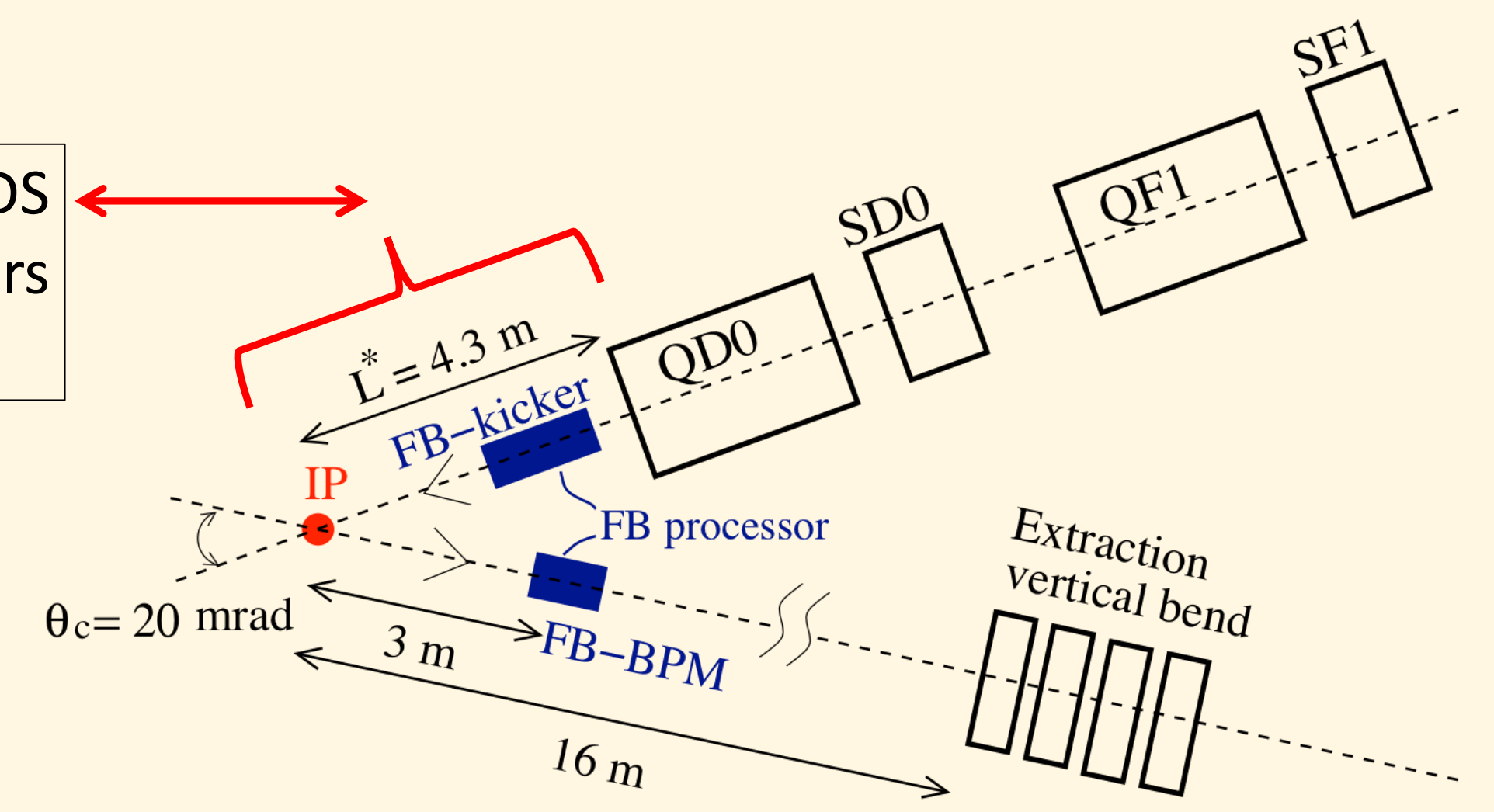
Abstract

In its currently- envisaged initial stage, the Compact Linear Collider (CLIC) will collide beams with a 380 GeV center of mass energy. To maintain the luminosity within a few percent of the design value, beam stability at the interaction point (IP) must be controlled at the sub-nanometer level. To help achieve such control, use of an intra-pulse IP feedback system is planned. With CLIC's very short bunch spacing of 0.5 ns, and nominal pulse duration of 176 ns, this feedback system presents a significant technical challenge. Furthermore, as part of a study to optimize the design of the beam delivery system (BDS), several L* configurations have been studied. In this paper, we will review the IP feedback simulations for the 380 GeV machine for two L* configurations, and compare luminosity recovery performance with that of the original L* configuration in the 3 TeV machine.

Introduction

- Current plans for CLIC involve phased commissioning with lower-energy lattice for 380 GeV collision energy.
- Previous studies focused on a BDS lattice designed for a 3 TeV collision energy.
- New BDS designs have two L* configurations:
 - 4.3 meters, 6 meters.
- Previous ground motion (GM) studies of 3 TeV machine performed for both 380 GeV designs.
- Intratrain IP feedback system used to correct perturbations from GM.

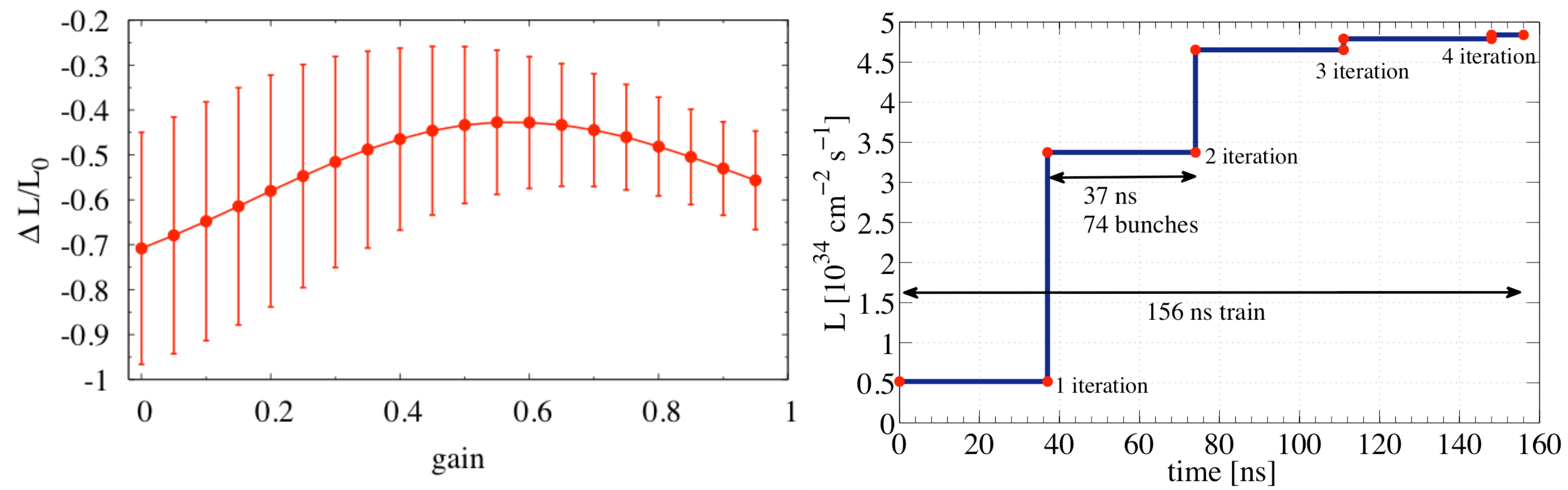
In the new 380 GeV BDS designs, L* is 4.3 meters or 6 meters.



CLIC interaction region, highlighting IP feedback kicker and BPM positions.

Previous Study

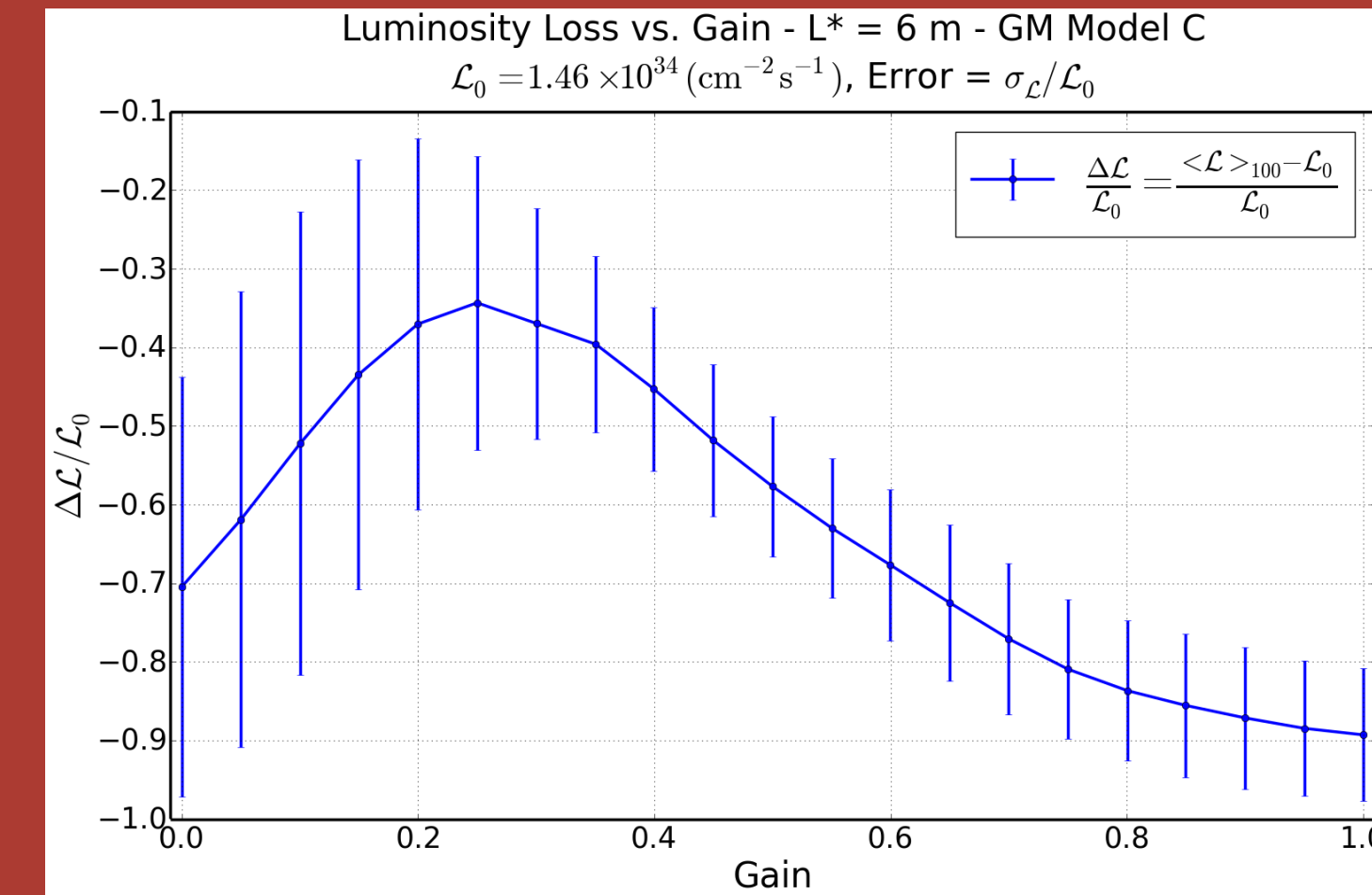
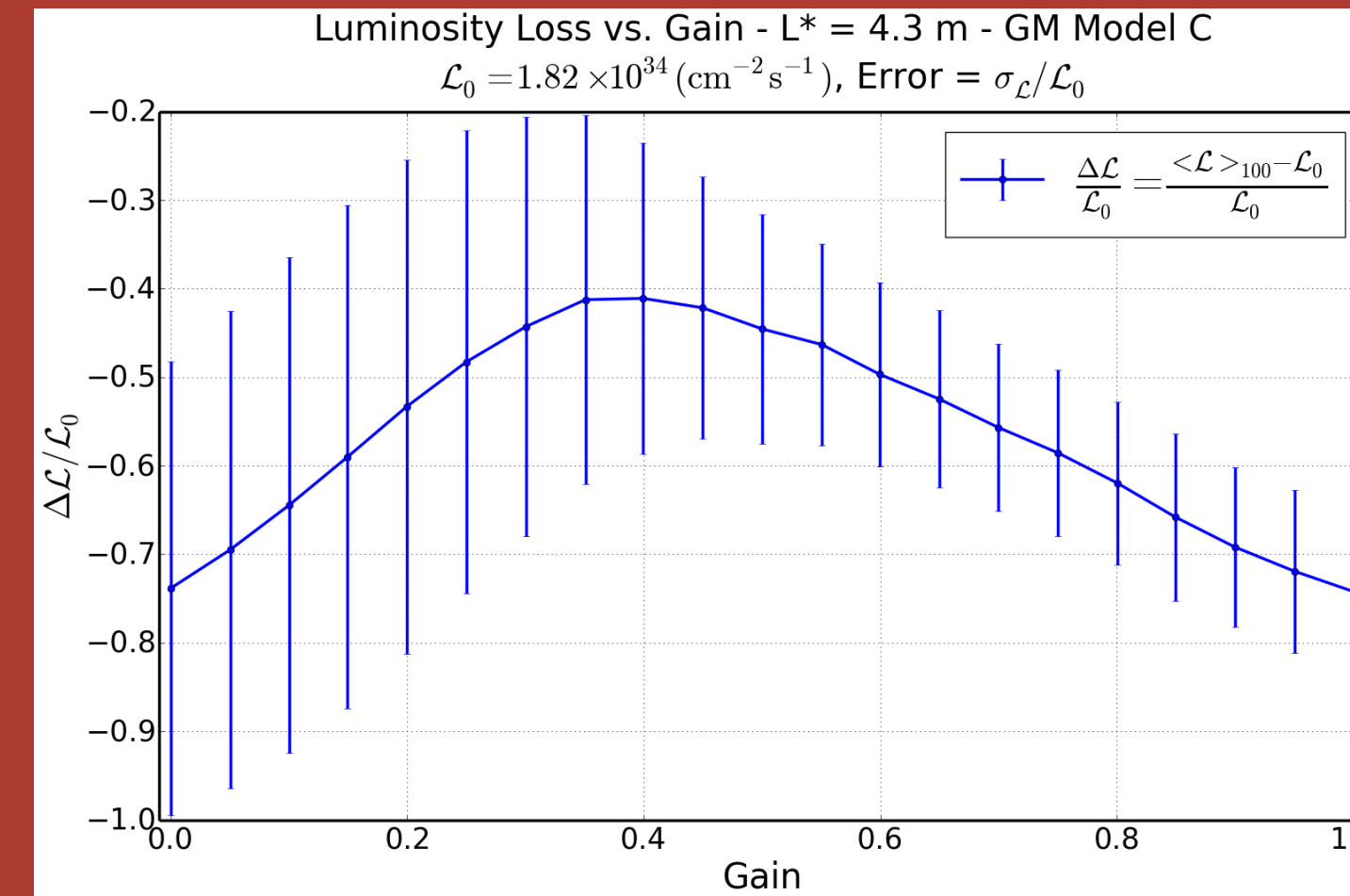
- Last study (Resta-López, 2010) focused on 4 GM models; A, B, C, and K.
 - Only model C plots shown.
- PLACET and GUINEA-PIG used for simulation studies.
- 3 TeV collision energy.
- Train length = 156 ns.
- Gain scan performed using 100 random seeds of GM.
- Luminosity recovery plotted for single seed using best gain value.



For GM Model C, previous studies achieved 4 correction iterations with the intratrain IP feedback system, and recovered significant luminosity.

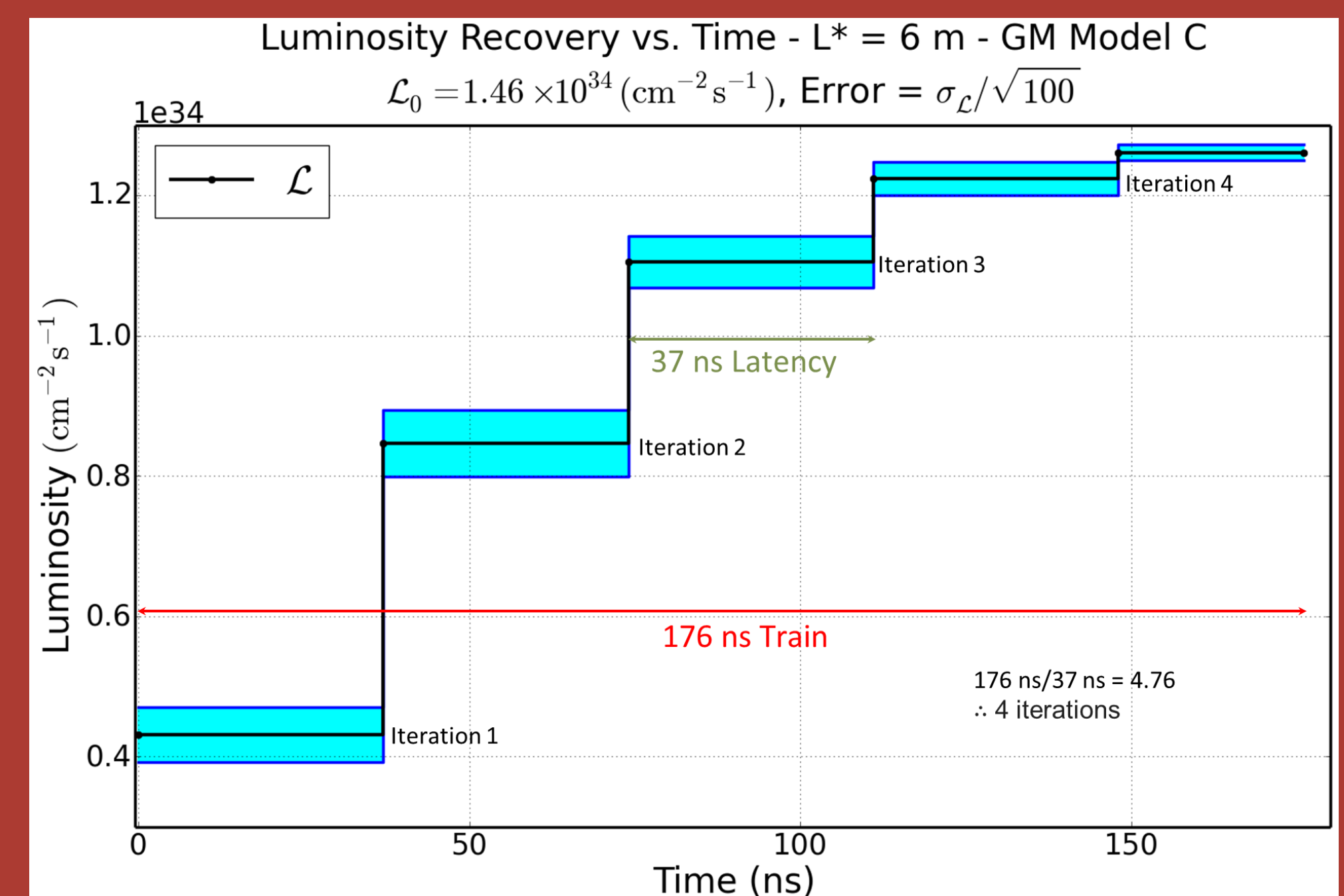
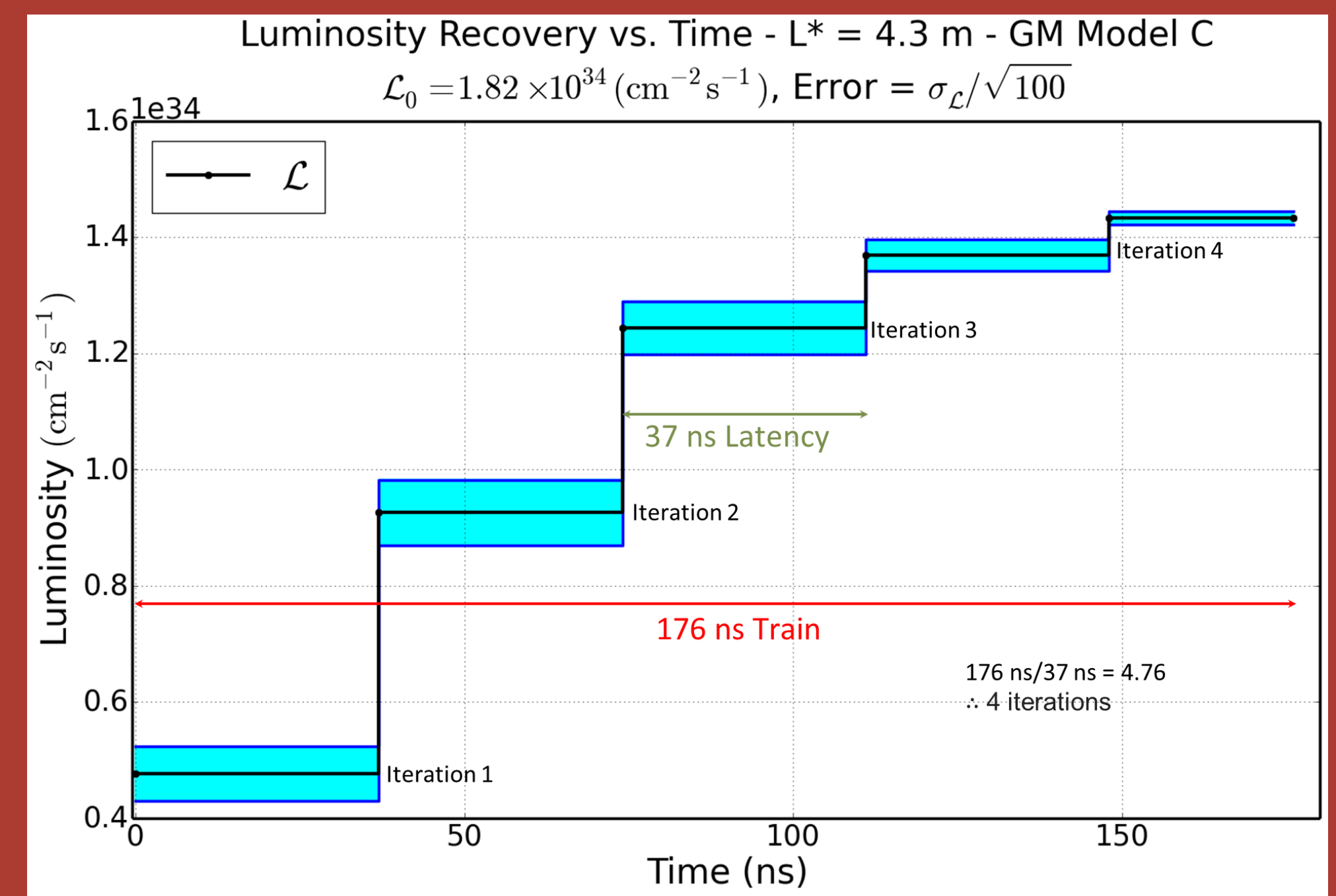
Current Study

- Focused on 5 GM models; A, B, C, D (also called B10), and K.
 - Only model C plots shown.
- LinSim framework of PLACET and GUINEA-PIG used for simulation studies.
- 380 GeV collision energy.
- Train length = 176 ns.
- Gain scan performed using 100 random seeds of GM.
- Luminosity recovery plotted for average luminosity from 100 random seeds using the best gain value.
 - Shaded error bands represent the error on the mean.



Results and Future Work

- Initial studies completed for all 5 GM models.
 - Model C plots shown.
 - All results summarized in table below.
- For L* = 4.3 m, luminosity recovery same or better for 380 GeV.
- For L* = 6 m, luminosity recovery similar to 3 TeV study results.
 - 380 GeV achieves as good or better results than 3 TeV.
 - Appears to be best overall results for all GM models.
- Simulation occasionally overcorrects, causing slight reduction in luminosity.
 - Looking for solutions to stop corrections at maximum luminosity.
- For future:
 - Looking at more complex systems, including more errors.
 - Applying ground motion to two independent beamlines.
 - Alternative algorithms for the IP feedback system.
- Please see proceedings for references.



GM Model	3 TeV, L* = 4.3 m (2010)	380 GeV L* = 4.3 m	380 GeV L* = 6 m
A	$\Delta L/L_0 \lesssim 0.1\%$	$\Delta L/L_0 \lesssim 0.1\%$	$\Delta L/L_0 \lesssim 0.1\%$
B	$\Delta L/L_0 \lesssim 3\%$	$\Delta L/L_0 \lesssim 3\%$	$\Delta L/L_0 \lesssim 3\%$
C	$\Delta L/L_0 \lesssim 45\%$	$\Delta L/L_0 \lesssim 42\%$	$\Delta L/L_0 \lesssim 35\%$
D	No Data	$\Delta L/L_0 \lesssim 9\%$	$\Delta L/L_0 \lesssim 6\%$
K	$\Delta L/L_0 \lesssim 35\%$	$\Delta L/L_0 \lesssim 20\%$	$\Delta L/L_0 \lesssim 18\%$

